Handheld Time-domain Electromagnetic Identification (TEMID) Sensor System

Carl V. Nelson

Johns Hopkins University
Applied Physics Laboratory

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Executive Summary

- **Purpose:** Develop a prototype handheld sensor system to reduce the false alarm rate associated with detection of medium and high metal content landmines.

- **Technical Approach:** The sensor concept incorporates advanced signal processing and a conventional time-domain electromagnetic induction metal detector.

- **Project Accomplishments:**
  - Developed state-of-the-art electromagnetic induction sensor
  - Conducted proof-of-concept laboratory tests
  - Conducted field tests using inert mines in a variety of soil types
  - Developed signal processing methodology for target discrimination

- **Project Conclusion:** Sensor system can differentiate mines from non-mine targets
Presentation Outline

- TEMID Project Objectives
- Time-domain Method
- Simulation Summary
- TEMID System Description
- Instrumentation Summary
- Signal Processing Summary
- Lab Test Data Summary
- Ft Belvoir Mine Lane Test Summary
- Ft AP Hill Field Test Summary
- Project Summary
TEMID Project Objectives

- Research, development, fabrication and test of a prototype handheld Time-domain Electromagnetic Identification (TEMID) sensor using Commercial Off-The-Shelf (COTS) technology.

- The overall objective is to improve the false alarm rate associated with the detection and identification of high and medium metal content mines, i.e., discriminate mines from the myriad of metallic clutter, such as nails, wire, and bullet shells.

- The TEMID sensor concept incorporates advanced signal processing to the basic time-domain handheld magnetic induction metal detector to improve its ability to discriminate specific types of mines and clutter.
Electromagnetic Induction Detector
Time-Domain Method
A. Very Early Time: Currents form in target conductor to preserve the original magnetic field before turn-off. Transmitter turn-off transients lie in this region.

B. Early Time: Resistive losses cause current to attenuate and time rate of change induce other currents.

C. Mid Time: Currents are diffusing through target.

D. Late Time: Spatial distribution of currents in target no longer change, all currents decay at rate determined by target size, conductivity & permeability.
Simulation Summary

- Used Vector Fields “Opera 3-D” to model plates of different conductivities and permeabilities
- FEM simulation software
- Program calculated current distribution in model as a function of time.
- Simulation was beneficial for visualizing target responses
- Applied step-up function magnetic field change to models
  - Step-down magnetic field not available in time for project
  - Step-up magnetic field complicated simulation result interpretation
    » Encountered round-off errors
- Experimented with different time steps
  - Found that a time step of 1 us was good compromise between processing speed and simulation results
- Simulation software had difficulty with shell models
- Simulation software helped to design transmitter and receiver coil design- confirmed experimental results
System Block Diagram of Hand-Held Time-Domain Electromagnetic Identification Sensor: TEMID Sensor
Laboratory Time Constant Apparatus

Power Supply

Transmitter Circuit

Test Target

Receiver Coil 20 cm

Transmitter Coil 1m x 1m
Instrumentation Summary

- Developed an inexpensive transmitter and receiver system
- Tested several transmitter and receiver coil designs
- Developed a unique transmitter coil design that enhances fast turn-off times
- Developed a receiver coil design that nulls soil background response and minimizes transmitter transient response
- Receiver design allows two concentric receiver coils to ‘coexist’ in the same circuit. Implications for receiver array designs.

Coil Design
- Transmitter: 25” x 45”: 8 loops
- Receivers: 16” x 16” and 4” x 4”: 2 each: 7 loops

Electronic System
- Gain: 10,000
- Frequency Response: 500KHz
- Dynamic Range: 12 bits
- Data Collection Time: 1-10 seconds (SNR dependent)
Instrumentation Summary (cont)

- Studied and compared Schiebel and APL Sensors

- **Important Sensor System Features:**
  - Can operate sensor system in high electrical noise environments
  - Bipolar transmitter current pulse: Zero net magnetic field
  - Measure target responses IO-20 us after transmitter turn-off
  - Fast recovery receiver amplifier (less than 100ns)
  - For this study, measurement results not critically dependent on transmitter and receiver construction details

- **Future Design Ideas**
  - Time variable gain amplifier to increase dynamic range
  - Custom-designed, high-speed, 16-bit ADC
  - Energy efficient transmitter design
  - Automatic transmitter power and receiver gain control
  - Improved transmitter and receiver coil design: better transient response characteristics and background nulling
  - Modify transmitter and receiver for small targets
  - Develop a receiver array for spatial measurements of magnetic induction
Simplified Comparison Between Schiebel and APL Mine Sensor Systems

Approx. APL BandPass: DC to 1 MHz; 80 dB

Approx. Schiebel BandPass: 160Hz - 12.5 KHz 75 dB

Frequency (Hz)

Schiebel Mine Sensor

Receiver Coil

Transmitter Pulse Blanking

Amp

Switch

Amp

Threshold Detection

Alarm

Metal Detection

TX Coil

Fixed Pulse Rate

Sync

Fixed Gain

Fixed Dynamic Range

APL Mine Sensor

TX Coil

Variable Pulse Rate- Fast for Search (600 Hz), Slow for ID (120 Hz)

Transmitter

Sync

Mux and ADC

Computer

Threshold Detection

Alarm

Metal Identification

Mine Classification

Receiver Coil

Large Dynamic Range

and High Sensitivity

Metal Detection
Laboratory Test Data Summary

- Documented differences between plates and shells (rings) representing different parts of a typical mine
- Documented differences between different metals: steel, brass, aluminum and copper
- During ‘Early Time’ decay response is a function of skin depth and hence material only. Currents are confined to outer layers of target.
- During ‘Mid Time’ and ‘Late Time’ eddy currents distribute themselves according to target geometry.
- For ‘Early Time’ and ‘Mid Time’ regions, the decay response is a weak function of target angle for angles up to about 20 degrees (for mines and mine-like targets in study).
- For ‘Late Time’ region, the decay response is a relatively stronger function of target angle. Exact relationship not established.
Typical Mine Physical Features

- Plate Response
- Shell Response
- Metal Mine
- Wall
- Top Plate
- Bottom Plate
Comparison Between Shells and Plates

Comparison between 13" dia. steel shell (16 gage x 2" H) and 13" dia. flat steel plate (1/16" thick). Data taken May 14, 1998.
Ring and Plate Response vs. Diameter

Ring diameters: 8” and 13” (1/16” wall)
Plate diameters: 8” and 13” (1/16” thick)
Date taken May 12, 1998

Graph showing sensor output (V, normalized at 70 us) vs. time (s) from 4 to 200 μs and 0.01 to 2 volts.
Steel Ring vs. Angle

May 17, 1998
Angle Response Study
Steel Ring 12" diameter
18" Receiver Coil diameter
Overplot of Four Normalized Sensor Responses at angles: 0, 8, 11 & 25 degrees

Sensor Output (V, normalized at 70 us)

Time (s)

Mid Time
Late Time
Sensor System 'Glitch'
Sensor Noise Floor
TM46 Mine vs. Angle

Overplots of sensor response as a function of angles: 0, 8, 13, and 28 degrees.
Observation: small differences, especially in late time region.
Time Constants vs. Depth for TM46 at Mine

Exp Fit of Data Over Listed Time Window

- Time Window 2-6 ms
  - Average = 1.01 ms
  - Std Dev = 63 us

- Time Window 50-200 us
  - Average = 54.7 us
  - Std Dev = 2.7 us

- Time Window 300-800 us
  - Average = 244 us
  - Std Dev = 4.5 us
Signal Processing Summary

- **Hardware/Firmware Signal Processing Summary**
  - Hardware trigger data collection at 60 Hz rate = 1 data scan
  - Data sampled at 2 us intervals
  - 4000 to 8000 data points collected during 1 scan
  - Between 10 - 1000 data scans are averaged to create final sensor signal

- **Direct use of sensor signal**
  - Do not require application of sensor transfer function
  - Do not need to integrate signal to get magnetic induction signal
  - Some improvement in SNR if signal is integrated; however, not needed or used in this study

- Multiple analysis methods for target discrimination
- **Simple conceptual analysis method: Decay Time Response**
  - Curve-fit data using exponential model over different time windows
  - Multiple exponential decay times characterize target response
  - Selection of time for amplitude normalization not critical
Signal Processing Summary (cont’d)

- **Double exponential line fits can be made on each series**
  - more closely matched data than single exponential
  - The two coefficients produced from each fit can be used to classify at the mine/no mine AND type of mine level

- **Multiple time series from each target can be parameterized and used as training data for an adaptive neuro fuzzy classifier**
  - Classifier is trained on targets in each type of background soil
  - “unknown” series from that soil are input to test trained classifier
  - Initial results show that classifier can identify type of mine and clutter

- **Both methods can separate mine versus no mine and classify to the mine level**
Preliminary Comparison of Curve Fit Time Constants for Various Mines and Clutter

Typical Example of Mine Data

Data Curve Fitted to Double Exponential:

\[ K_0 + K_1 \exp(-t/K_2) + K_3 \exp(-t/K_4) \]

't' is time in usec; \( K_2 \) & \( K_4 \) are the decay time constants for the target

![Graph showing raw data and curve fit for different mines and clutter types.](image-url)
Training Adaptive Neuro System

Training Data

Parameterize

Train Adaptive Neuro Fuzzy System

Training Results
Evaluating Unknown Time Constants With Trained Adaptive Neuro Fuzzy System

Unknowns

Result

1.0168  TM46

1.9788  VAL

3.0011  Coke Can

Evaluate With Fuzzy Classifier
Ft Belvoir Test Summary

- **Test Objectives:**
  - Pretest system before final field testing at Ft AP Hill
  - Collect target data in different soil types
  - Collect data at different sensor heights above target
  - Test effects of soil on sensor/target response
  - Test effectiveness of nulling techniques

- **July 15, 16 & 17 1998**

- **Indoor Mine Test Lanes**
  - Dry clay soil and magnetic sand
  - Transmitter Coil: 25” x 25”: 7 loops
  - Receiver Coil: 17.5” x 17.5”: 4 loops
  - Null Coil: 4” diameter: 6 loops
  - Targets: FFV028, MI6, M20, M5, TM46, Small Steel Ball, AL drink can, Steel Tape Measure, Steel Test Target
  - Data Collection System: FieldWorks portable computer & MicroStar ADC
Ft. Belvoir Summary

July 17, 1998, Ft Belvoir Mine Lanes
Targets 3-4.5" from tx, on top of dirt
normalized at 100us
Dry Clay Dirt (Lane 6)
Sensor system and data acquisition software worked well

For targets studied, “Easy” to visually discriminate between mines and clutter targets

For shallow buried mines, very small changes in time decay response

Variation in decay time constant was about 5-10% for different soil types (dry clay & magnetic sand), covered vs uncovered, and target distance from sensor

Lessons Learned:
- Increase data collection time from 4 ms to 8 ms
- Boost transmitter power to look at ‘Late Time’ signals
- Cumbersome background subtraction method- designed new receiver coil for automatic background subtraction
- No real need to cover targets with soil
- Target to sensor distance of 1-5 inches OK for consistent results
- Focused attention on ‘Mid Time’ region and transition to ‘Late Time’ region (100 us to 3 ms) of decay response
- Small amount of drift in electronics- minor change in new version should fix problem: problem does not effect time constant calculation only data processing steps and graphic visualization
Clay Soil Training Results
Magnetic Soil Training Results

Diagram showing magnetic soil training results with various labeled points such as 'm20 mag', 'm16 mag', 'tm46 mag', and 'sw mag'.
Classification With Adaptive Neuro Fuzzy System

25 Block Averages Collected
24 Used Used Train System (Results Seen In Following Two Charts)

1 Used as Unknown Not Used in Training

July 1998 Ft. Belvoir

Unknown Results

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<tr>
<td>1</td>
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<tr>
<td>2</td>
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<tr>
<td>3</td>
<td>FFV028</td>
</tr>
<tr>
<td>4</td>
<td>M16</td>
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<td>5</td>
<td>Small AP</td>
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<table>
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</tr>
<tr>
<td>3 M16</td>
</tr>
<tr>
<td>2.8801</td>
</tr>
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Ft AP Hill Test Summary

• Test Objectives
  – Final demonstration of prototype TEMID sensor system
  – Collect data from multiple mine, mine-like and clutter targets

• August 4 & 5, 1998

• Ft AP Hill 71A range, JUXOCO and ‘special test area’

• Data Acquisition System the same as Ft Belvior test except for improved transmitter and receiver design

• Soil Types:
  – JUXOCO range- hard, dry clay
  – ‘Special test area’- sandy soil in treed area 50’ south of range house

• Target to sensor distance: 2-7 inches

• Mine Targets: FFV028, M16, M20, M21, M6, M16, Val69, TM47, TM46

• Clutter Targets: All fe clutter (90 gr), A7 fe clutter (306 gr), Ml6 cartridge, Ml6 cartridge clip, 50 cal cartridge, coffee can, Al drink can, 1/4” lag screw, small tools
Summary AP Hill

For AP Hill: August 4 & 5 1998
Mine Data Normalized with Respect to TM 46 Mine
Target to Sensor Distance: 4-7 inches

Sensor Output (normalized at 50 ns)

Sensor 'Glitch'
Large/Small Coil Interaction
Aug 4 Clutter vs. TM46

August 4 & 5 1998, FT AP Hill

Sensor Output (V, normalized at 50 us)

5 6 7 8 9 10^{-4} 2 3 4 5 6 7 8 9 10^{-3}

Time (s)

A7 Clutter 306 gr
TM46 AT
OZM3 AP
A11 Clutter 90 gr

Detection System 'Glitch'
Battle Field Clutter vs. M21 Mine

August 5, 1998, Ft AP Hill
Clutter Targets + M21 AT Mine
Small Receiver Coil
Sandy soil

Sensor Output (V, normalized at 50 us)

Time (s)
Summary Time Constant Plots

[Graph showing various targets with time constants and error bars]

Summary of Time Constants for Various Targets
Mid to Long Time Region
+/- 5% error bars added

Summary of Time Constants of Various Targets
Short to Mid Time Region
+/- 5% error bars
Ft AP Hill Test Data Summary

- For AT and AP mines in test study, ‘easy’ to discriminate between mines and clutter: Mine vs No Mine
- Under these ‘ideal’ test conditions, we can discriminate between different mines, even mines that appear very similar, e.g., TM46 and TM47 or M20 and M21
- Classify mine types and clutter using time constant plots
  - Selected three time windows: 70 - 200 us; 300 - 700 us; and 800 us - 3 ms
  - Exponential curve fit data in selected time windows
  - Normalization of data not required for curve fitting
  - Normalization of data good for graphic comparison of data
  - Mine and clutter time constants substantially different
Project Summary

- Investigated Medium/High Metal Content Mines and Mine-like Targets
- Developed instrumentation to measure target time-domain decay responses over time range of 20 us to 16 ms
- Developed Two Classification Methods for Discriminating Mines from Non-Mines
- Major Target Signal Characteristics
  - ‘Good’ starting time around 50-100 us
  - ‘Good’ stopping time around 10-20 ms
- Exponential curve fitting method works well for Mine vs No Mine Discrimination
  - Related to mine physics
  - Three or more time windows for curve fitting
  - No need to normalize data
- Adaptive neuro-fuzzy classifier results very encouraging
  - Classify to the type of mine level in clay and magnetic soil
. All program responsibilities met
  - technical meetings
  - status reviews (multiple)
  - Final report delayed due to low metal content detection task that was added to contract

. Based on analyses performed on this contract, time domain technology appears very promising for insertion into vehicle and hand held systems